## Optimization Algorithms Weekly Exercises 9

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## 1  $(1 + \lambda)$ -ES

The  $(1 + \lambda)$ -ES is one of the simplest stochastic search methods. Implement this method (for given parameters  $\sigma$  and  $\lambda$ ).

Test  $(1+\lambda)$ -ES on the simple  $n=2$ -dimensional squared cost  $f(x) = x^{\top}Cx$ , where C is diagonal with entries  $C_{ii} = c^{\frac{i-1}{n-1}}$ and conditioning  $c = 10$ . Initialize the center with  $\hat{x}_0 = (2, 2)$ .

- a) For large  $\lambda = 100$  and fairly small  $\sigma \approx 0.02$ , how does the typical trace of the method look like? (The typical path the method takes in this 2D problem?)
- b) For  $\lambda = 1$ , roughly what is the probability of improvement of each step in the early phase (say, the very first step) of optimization?
- c) Qualitatively, what is the probability of improvement in the "mid-phase" (which should be clear from the typical path)? (Smaller or larger than in the early phase?) How would that change with increasing dimensions n?

## 2 No Free Lunch (NFL)

You are given an optimization problem where the search space is the discrete set  $X = \{1, \ldots, 10\}$  of size 10, and the cost space Y is the set of integers  $\{1,\ldots,10\}$ . The unknown cost function  $f: X \to Y$  is distributed by  $P(f)$  and we assume that you (or the algorithm) knows  $P(f)$  apriori. (The equivalence of not knowing anything about f would be  $P(f)$  is i.i.d. uniform (with maximal entropy), which is the NFL condition. To solve this exercise, you do not need to know NFL in detail – if you are interested, I am uploading correspondings slides on ISIS.)

a) If you know that  $f$ -values of neighboring  $x$  can only differ by 1, i.e.,

$$
\forall_{x_1, x_2 \in X}: \ |x_1 - x_2| \leq 1 \Rightarrow |f(x_1) - f(x_2)| \leq 1,
$$

and all possible f are equally likely, how would you design an (optimal?) optimization algorithm?

- b) If you additionally to the above know that the function  $f$  aquires all values in  $Y$  somewhere (i.e., the image of f equals Y), and all possible f are equally likely, how would you design an (optimal!) optimization algorithm?
- c) Bonus/Optional: Now, if you know that f-values of neighboring x can only differ by 2, but again f must be bijective (and all possible f are equally likely), how would you design an (optimal?) optimization algorithm?

The exercises are also meant to illustrate what it means to maintain a *belief*  $P(f|D)$  over the function, given observed data. Can you indicate what beliefs or similar your proposed algorithms maintain while exploring the function?