

MOA-NET: SELF-SUPERVISED MOTION SEGMENTATION

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MOTION SEGMENTATION

- P Bideau, E Learned-Miller, ECCV 2016:
 It's moving! A probabilistic model for causal motion segmentation
- P Bideau, A RoyChoudhury, R Menon, E Learned-Miller, CVPR 2018: The best of both worlds: Combining CNNs and geometric constraints for hierarchical motion segmentation
- P Bideau, R Menon, E Learned-Miller, Workshop ECCV 2018:
 MoA-Net: Unsupervised Motion Segmentation

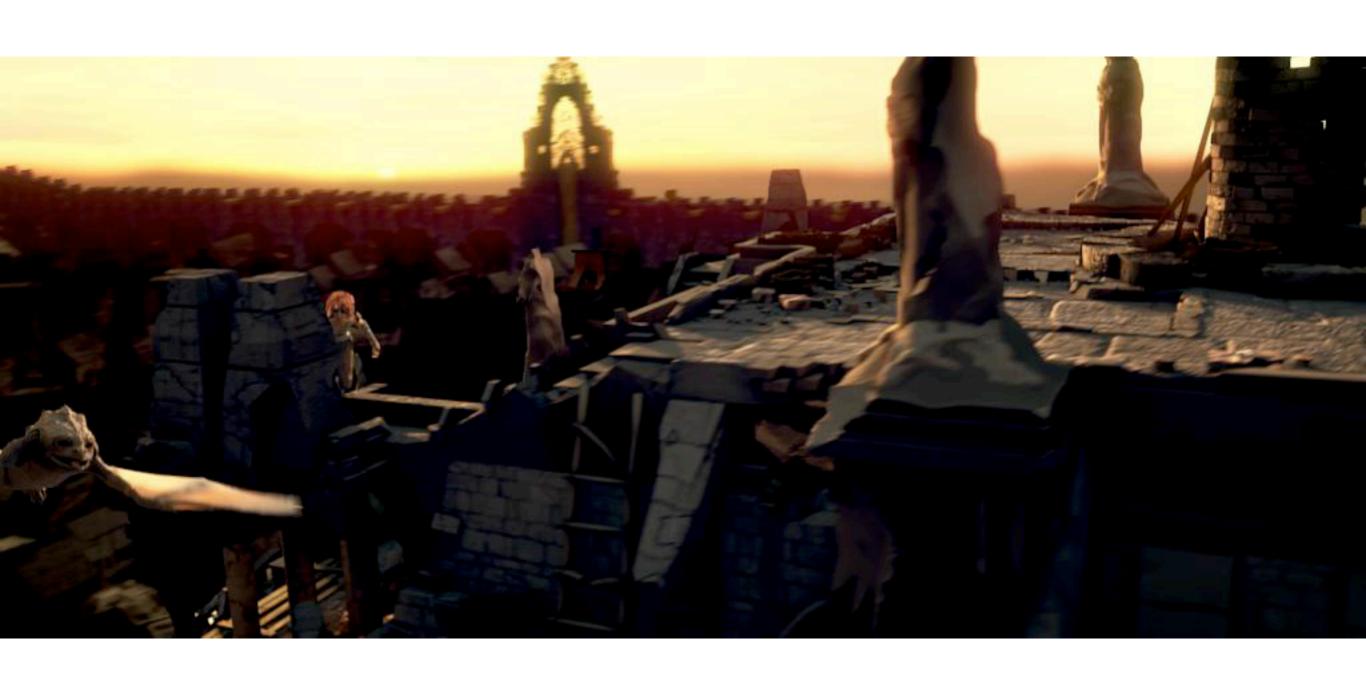
OVERVIEW

Motivation

How do humans know

what is moving in the world and what is not?

- Approach: Motion Segmentation
 - Rotation compensation
 - Learning Motion Patterns: MoA-Net
- Results
- Future Research Questions



- stationary scene
- moving object
- **no** observer motion

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- moving object
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All motions result in changes of the retinal image.

What is the problem about retinal image motion?

- photoreceptors are slow
- motion detection in our brain is challenging

Need to stabilize the image, to reduce retinal image motion



OVERVIEW

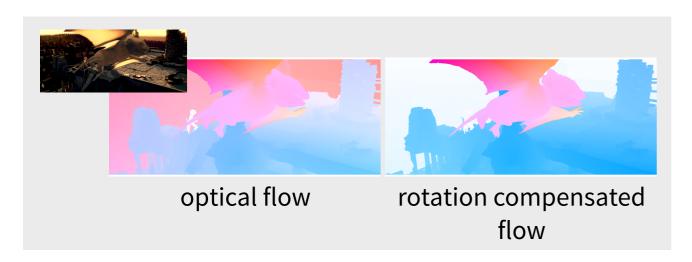
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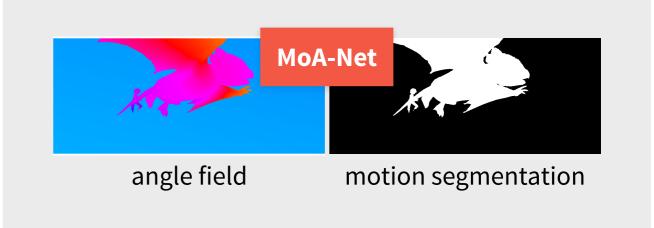
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APPROACH: MOTION SEGMENTATION

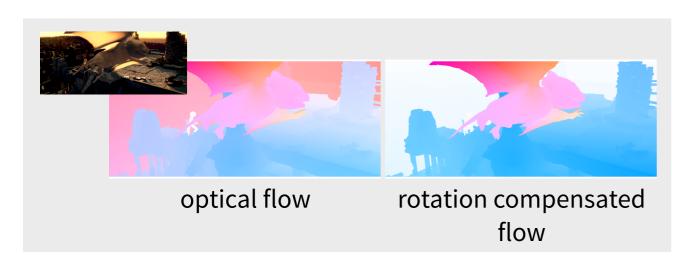




step 1: rotation compensation

step 2: motion segmentation

APPROACH: MOTION SEGMENTATION





step 1: rotation compensation

step 2: motion segmentation

ROTATION COMPENSATION



- rotation + translation
- optical flow magnitude is dependent on scene depth
- optical flow angle is dependent on scene depth



- translation
- optical flow magnitude is dependent on scene depth
- optical flow angle is independent of scene depth

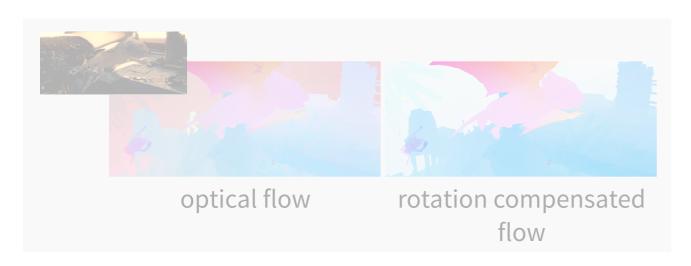
ROTATION COMPENSATION

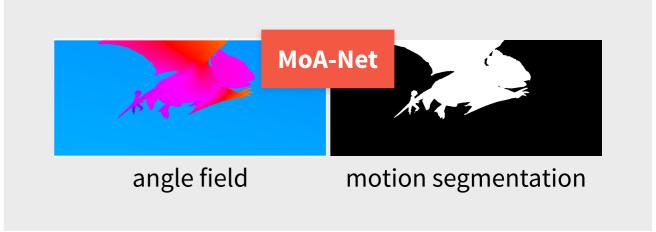
only camera translation and object motion



optical flow angle field

MOTION SEGMENTATION

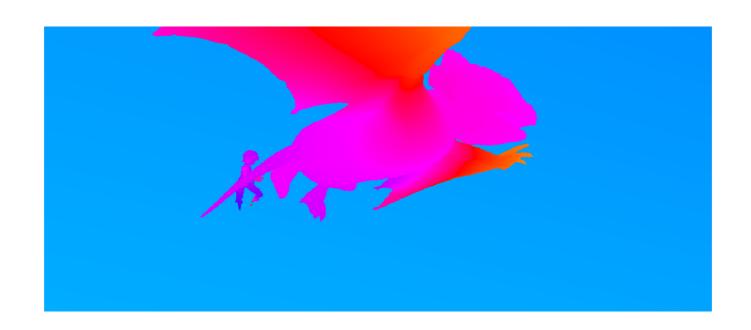




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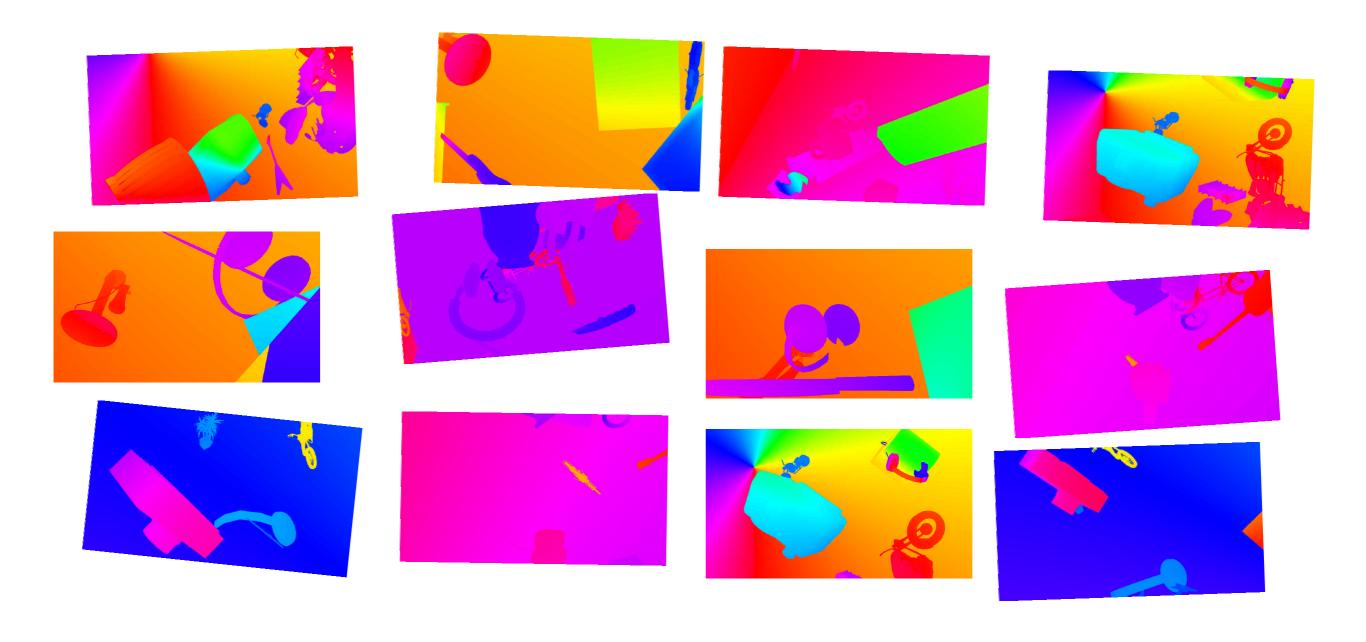
step 2: motion segmentation

MOTION SEGMENTATION DEFINITION



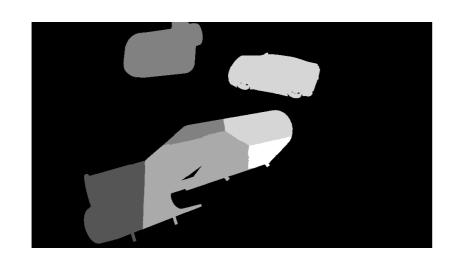
Def.: Moving Object

A moving object is a connected image region that undergoes some independent motion. The connected image region can be of any size and shape.

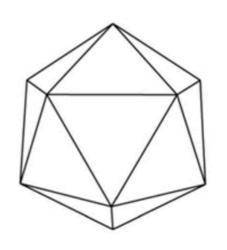




- Generating connected object regions.
- Splitting each object into n subregions.
- Assigning to each motion region a translational 3D direction.
- Smoothing motion boundaries inside moving objects.
- Adding random gaussian noise.



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$$\theta = \operatorname{atan}(-fV + yW, -fU + xW)$$
$$= \operatorname{atan}(-V' + yW, -U' + xW)$$



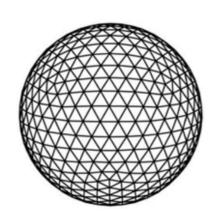
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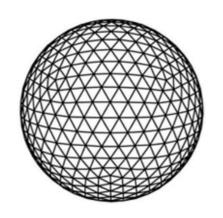
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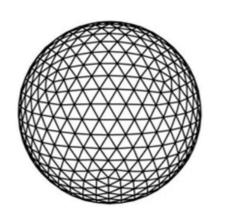


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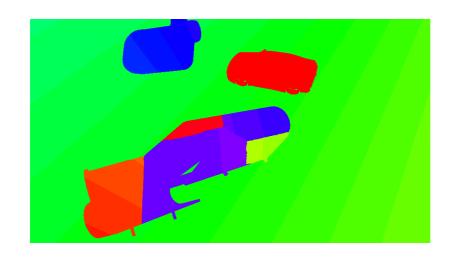


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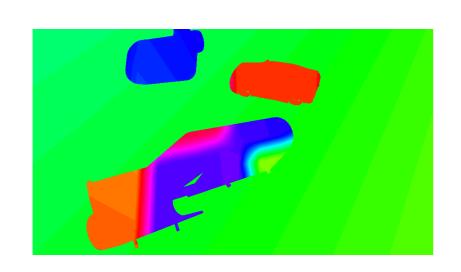


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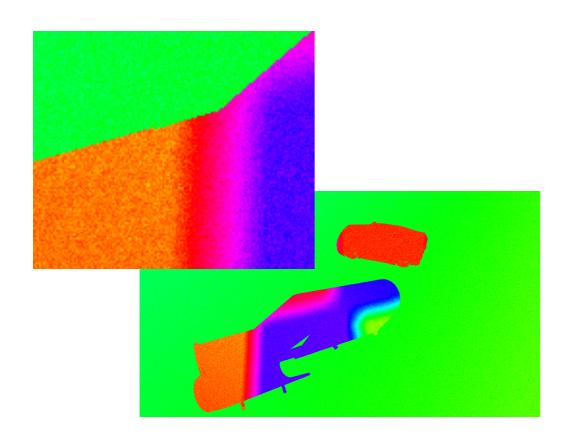
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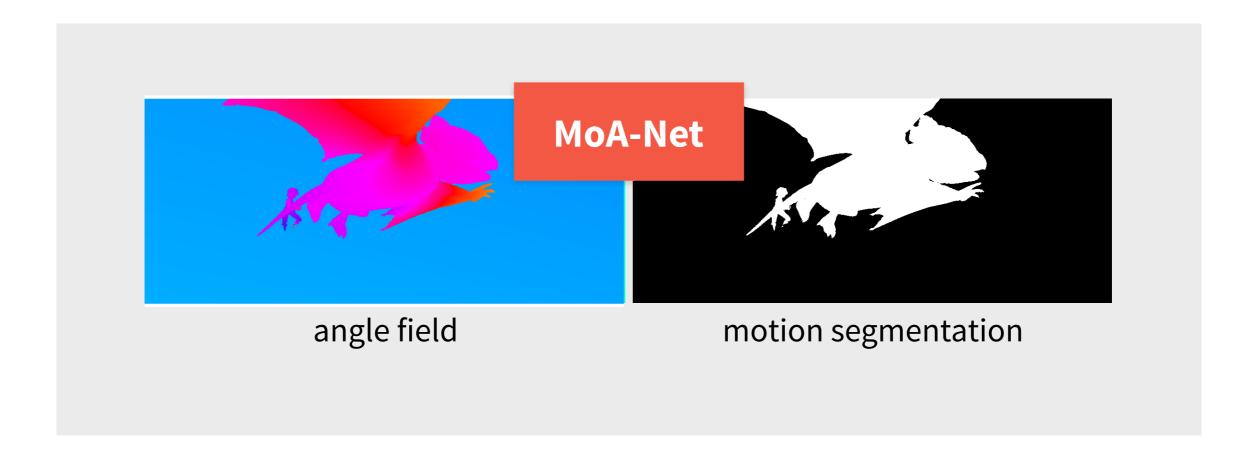


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MOTION SEGMENTATION



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SEGMENTATION RESULTS

video frame ground truth Jain et al. Tokmakov et al. ours

SEGMENTATION RESULTS

	Motion Segmentation: Sintel					
	J Mean	J Recall	J Decay	F Mean	F Recall	F Decay
	†	\uparrow	\downarrow	\uparrow	†	\
Tokmakov [1, 2]	50.46	55.43	44.50	53.43	35.04	39.75
Jain et al. [3]	29.63	24.98	36.07	28.65	14.70	31.20
ours	54.77	54.47	26.57	59.71	61.38	14.79

SEGMENTATION RESULTS



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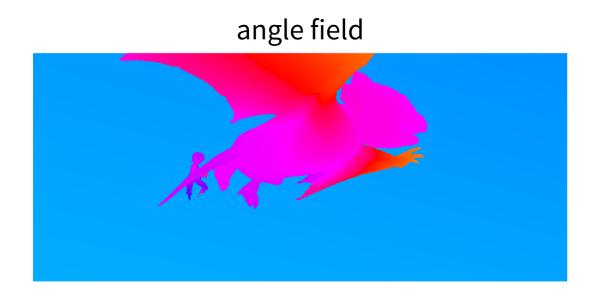
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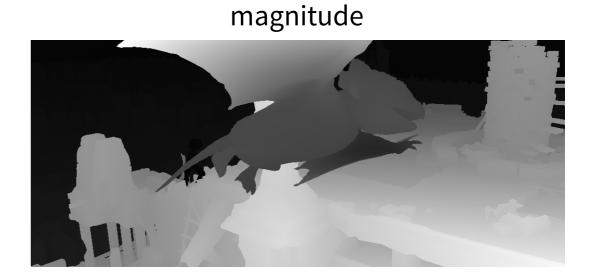
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FUTURE RESEARCH QUESTIONS





- Importance of the flow magnitude for
 - estimating the scene depth
 - dealing with estimated (noisy) optical flow

-QUESTIONS-